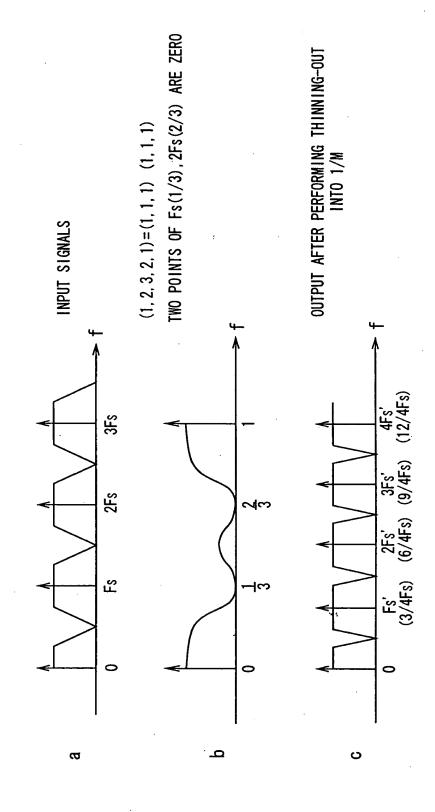
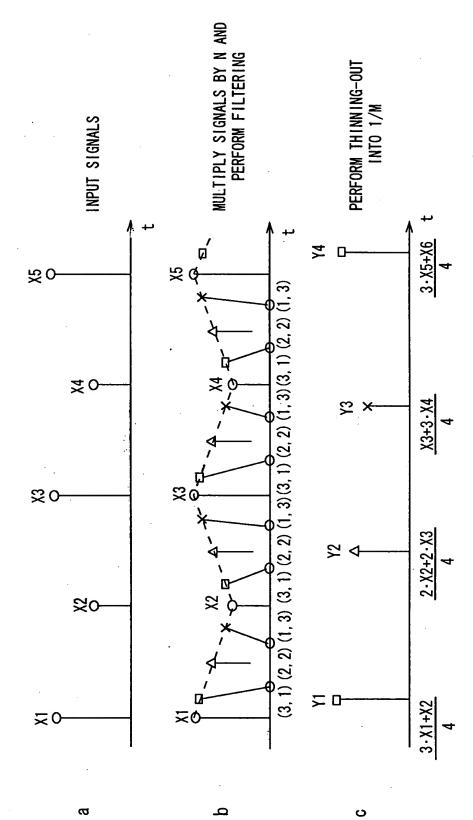


F1G. 1



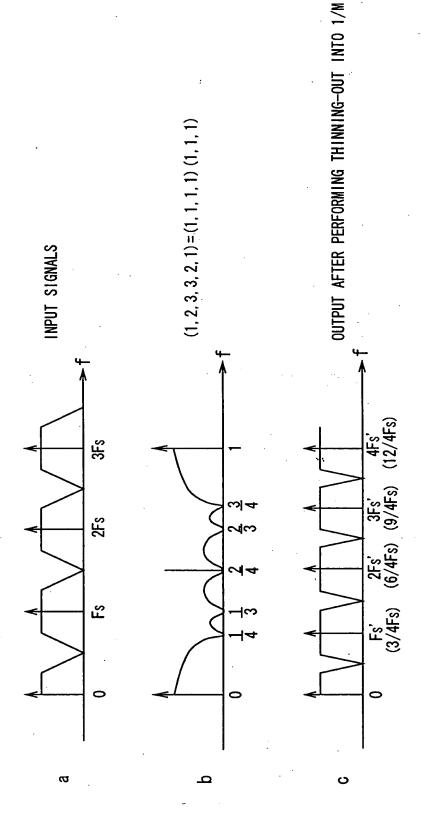


F16.

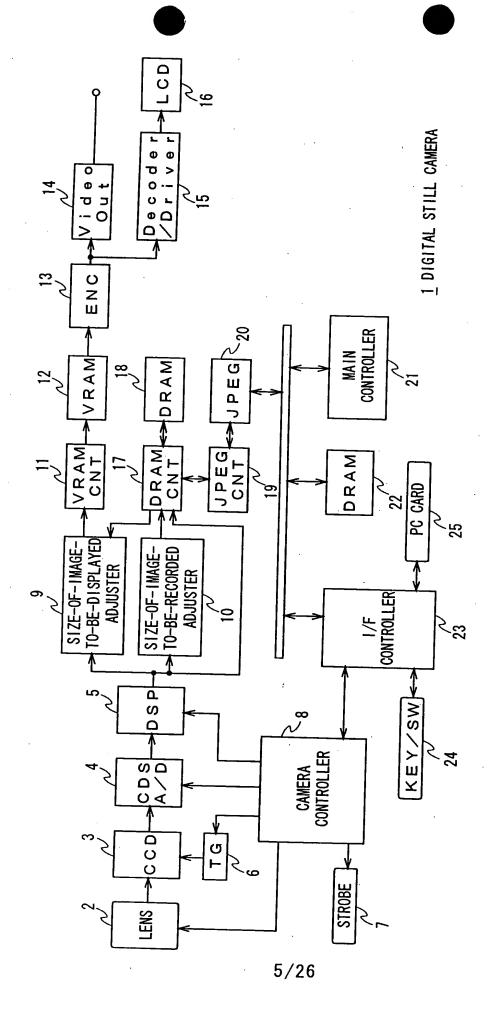


AN EXAMPLE OF REDUCING INPUT SIGNALS TO 3/4 (M=4, N=3) (CURVE INTERPOLATON)

F1G. 3

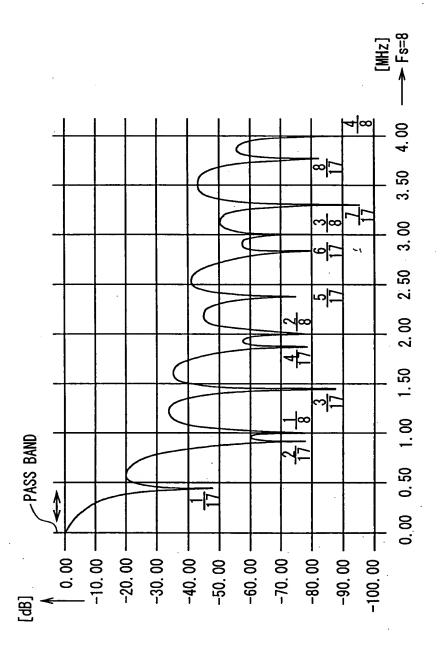


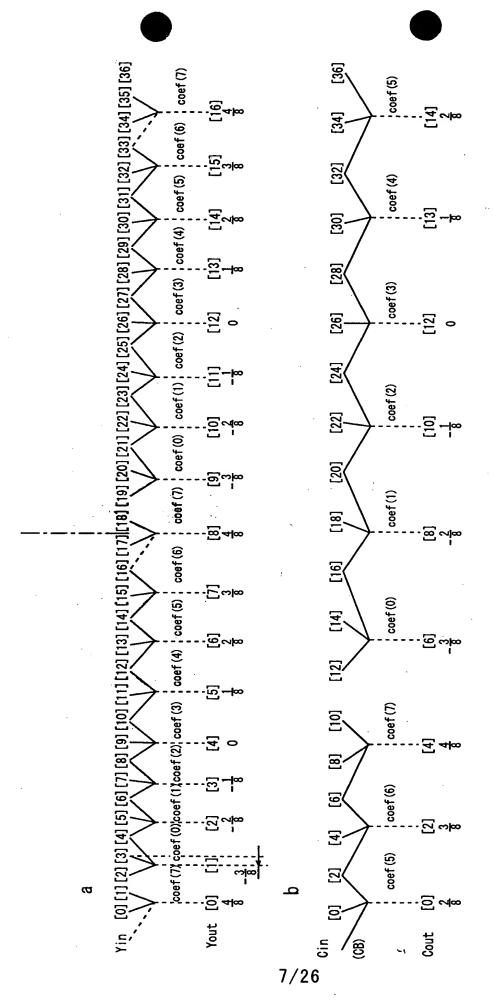
F16



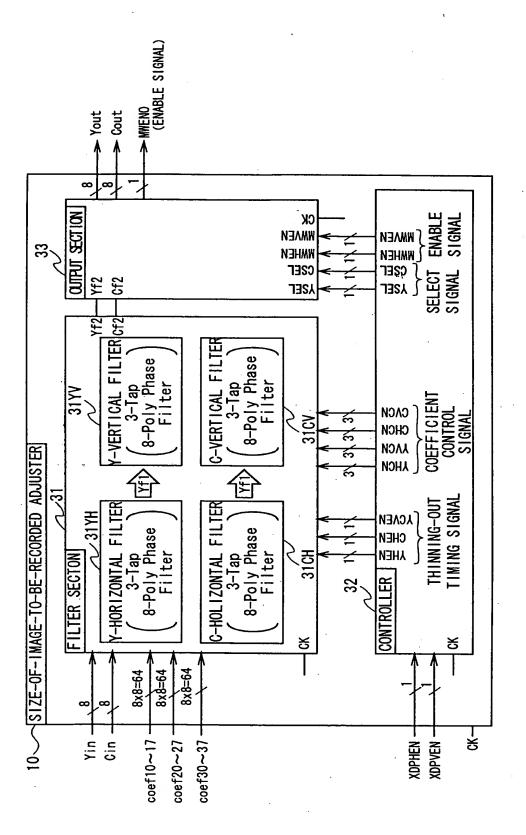
F1G. 5



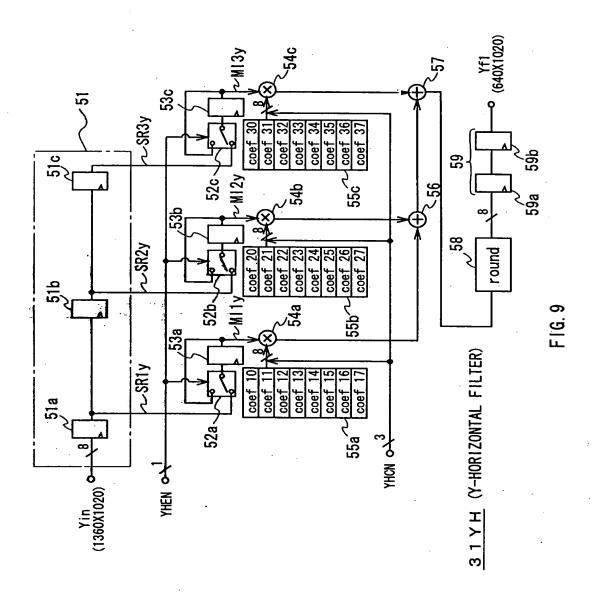


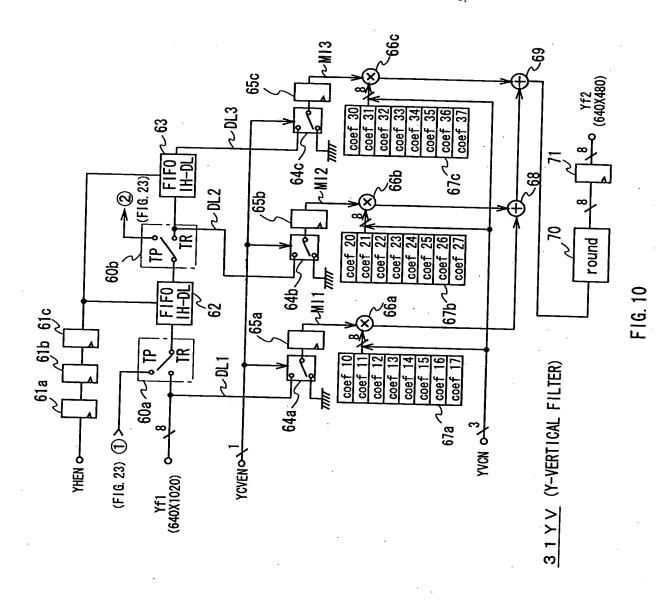


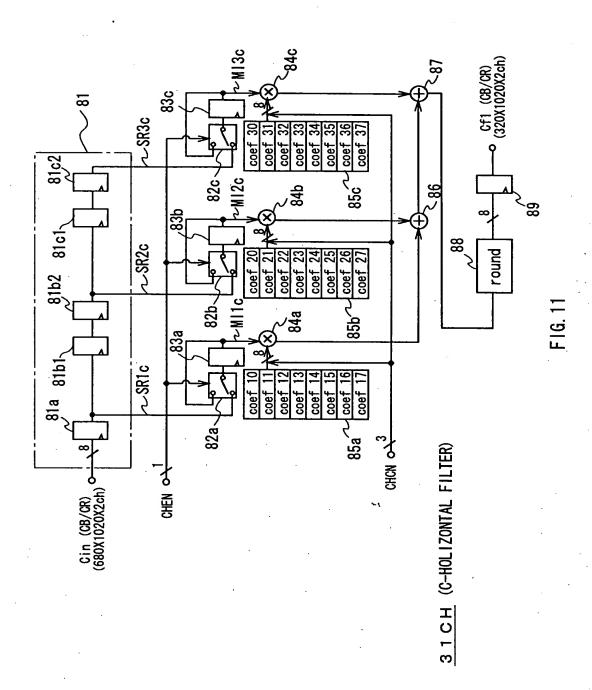
F1G. 7

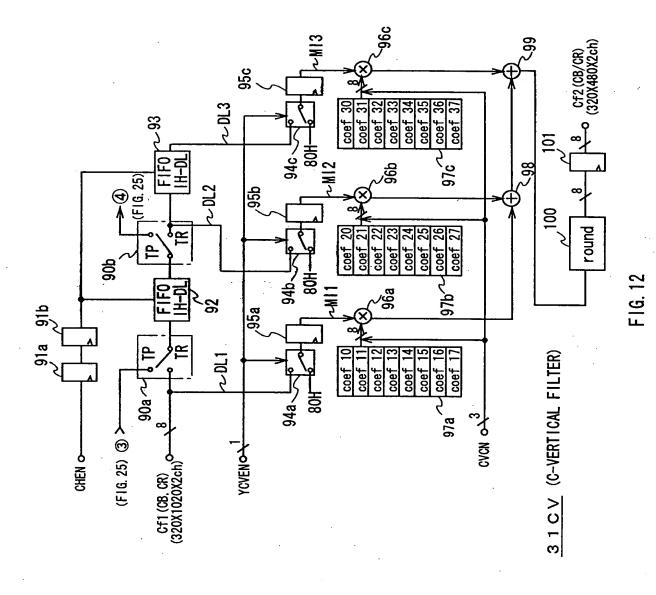


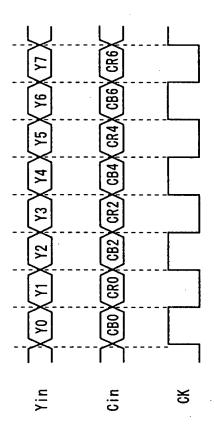
3 91 -



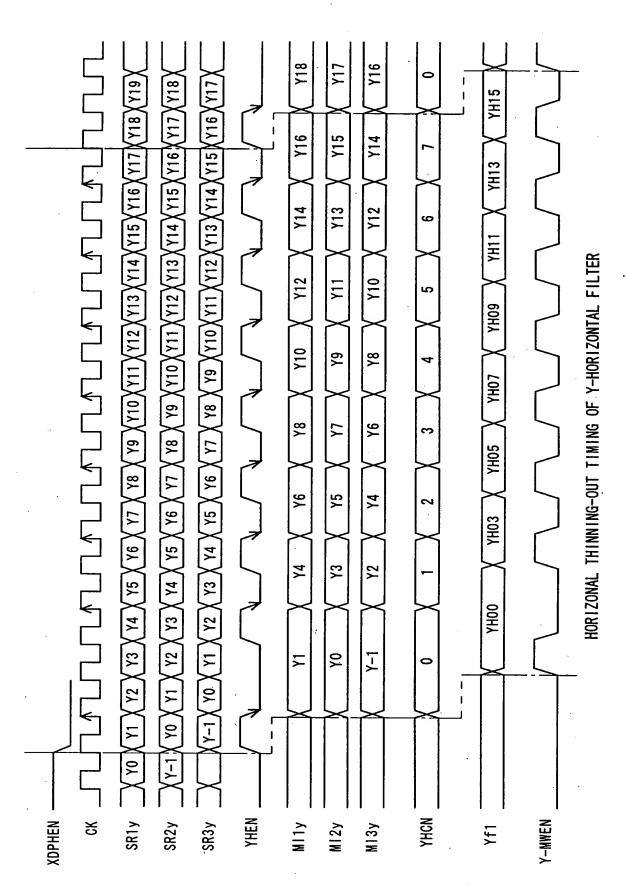








F16. 1



F1G. 14

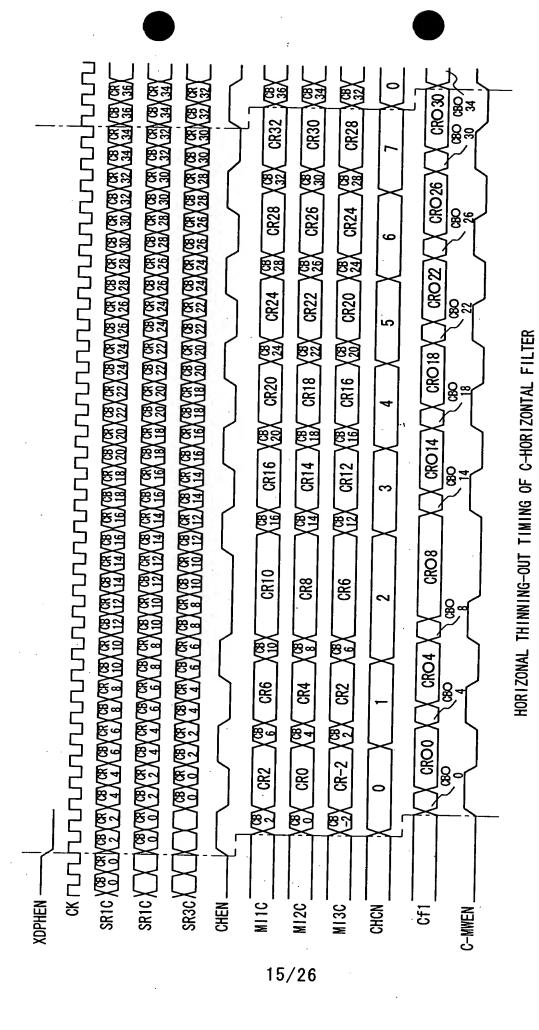
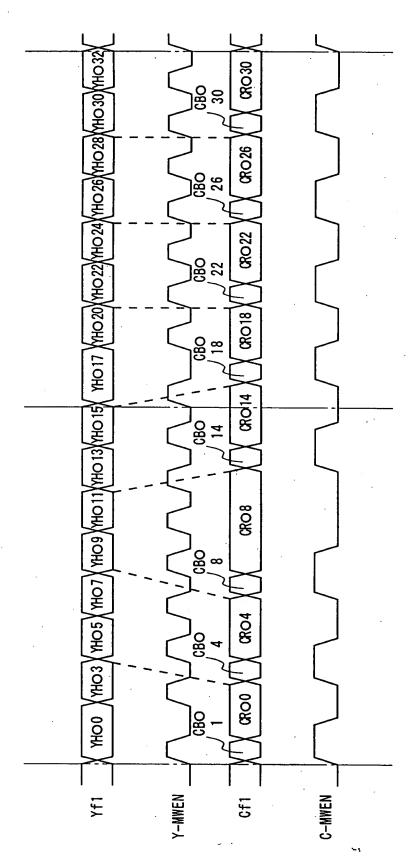
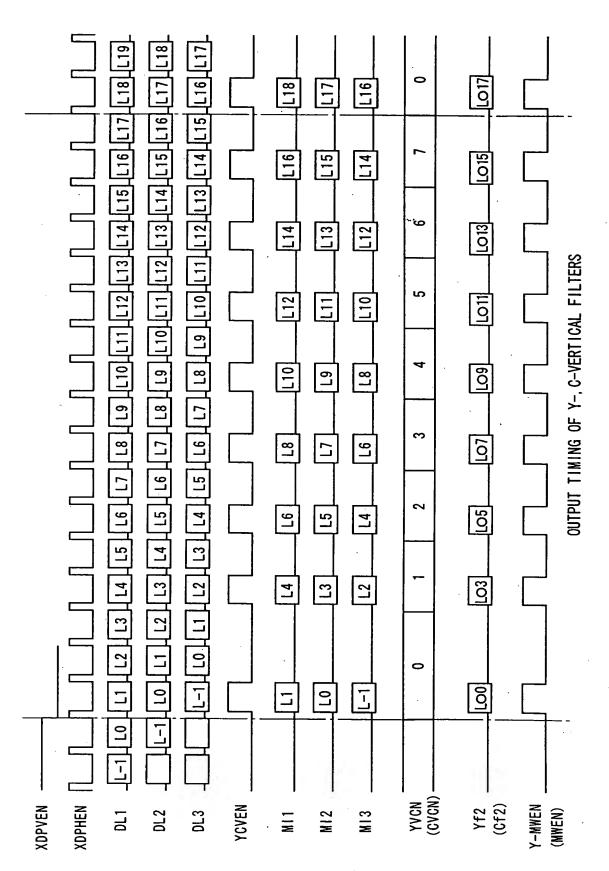


FIG 15

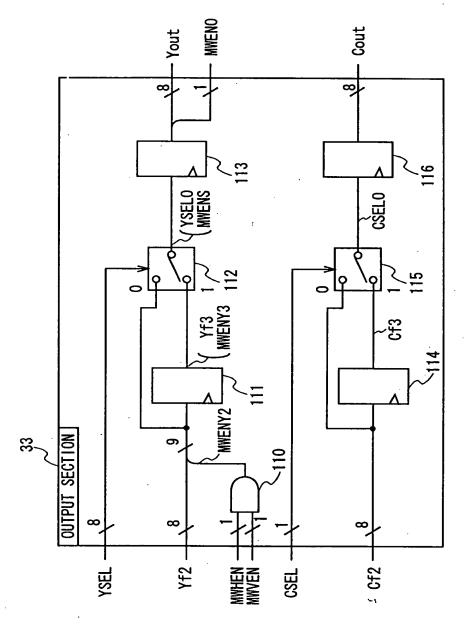


OUTPUT TIMING OF Y-, C-HOLIZONTAL FILTERS

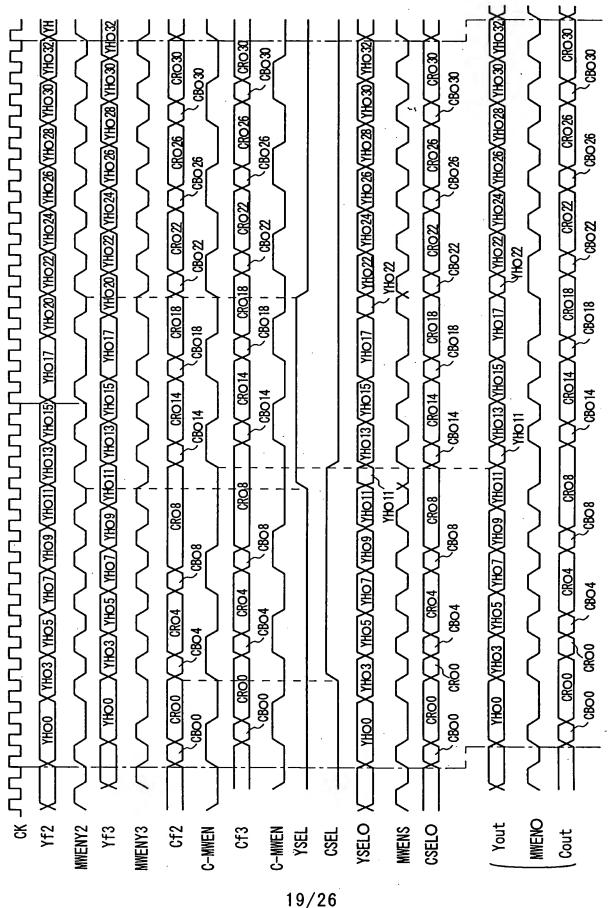
-1<u>6</u>. 16



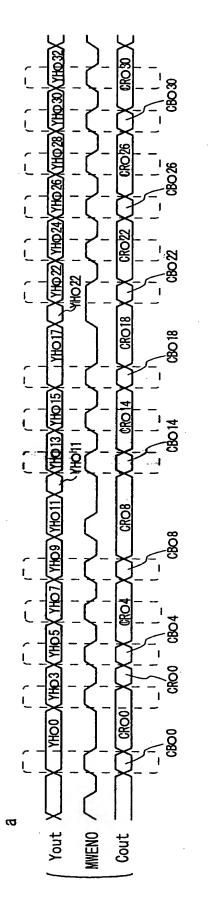
F16.1



F1G 18

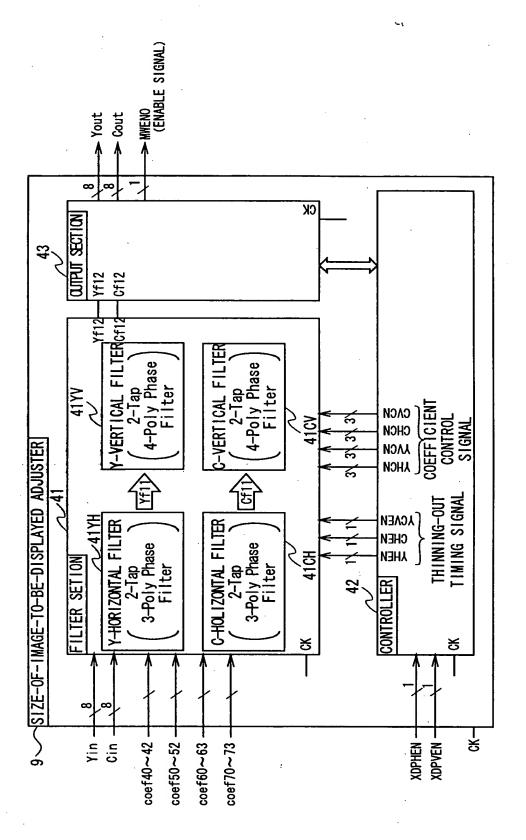


F1G. 19

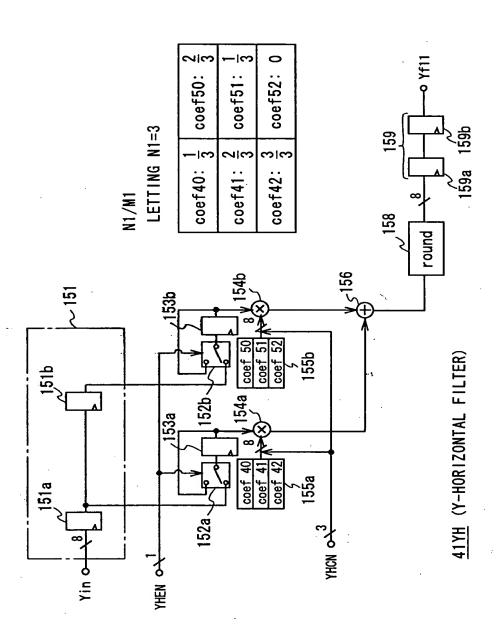


	32	SS 30 80	
YHO	30	0BO 30	
꾟	28	CRO 26	
욷	26	CBO 26	
YHO	24	CRO 22	
W	22	CBO 22	
XHO	20	CRO 18	
 YHO \	17	0BO 180	
사	15	S2 4	
YHO	13	CBO 14	
욌	=	CRO 8	
윉	6) 8 8	
웆	7	CRO 4	
윉	5	CBO 4	
윉	က	CRO 0	
옷	0	OBO 0	

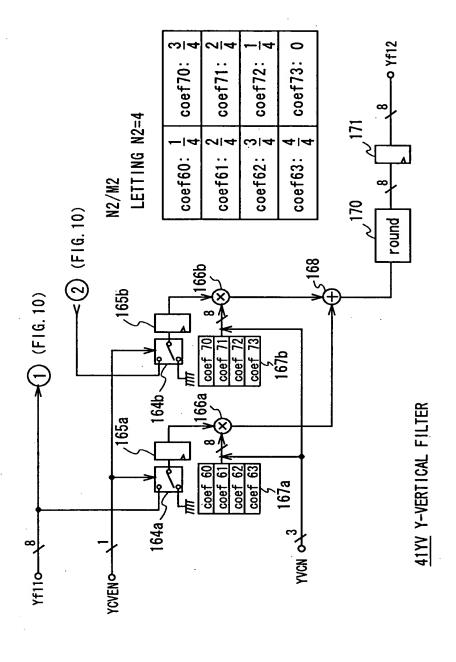
F16, 20



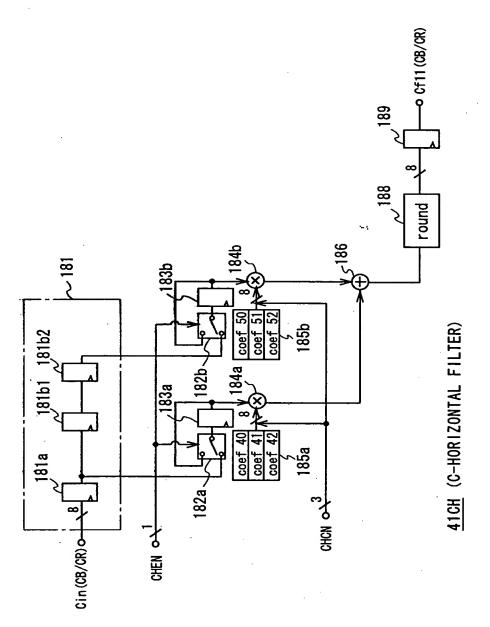
F16.2



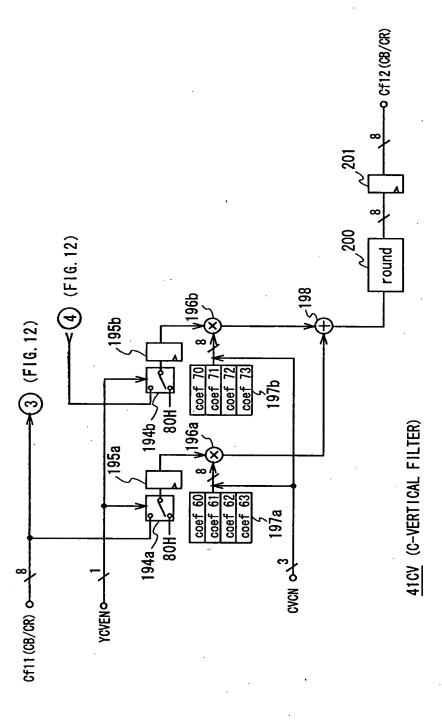
F1G. 22



F1G. 23



F16. 24



F1G 2